Lattice Recurrent Unit

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May 30, 2017

A plethora of data is sequential in nature

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A plethora of data is **sequential** in nature ⇒ The **order** is important

and because the permutations increase **factorially** (n!) with the number of data points (n)

We might lose information if the order is not preserved





$$P\left(\left\|x_{t}\right\|_{x_{1:t-1}}\right)$$

• Function Approximator: A model that can approximate such distributions.

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⇒ Neural Networks

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⇒ Increase **depth** of Neural Networks.

- Order Preserving: Use order-information as well to predict.
 - ⇒ Deep Recurrent Neural Networks (**Deep RNNs**)

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 - ⇒ Deep Recurrent Neural Networks (Deep RNNs)
- Trainable: Estimate accurate functions in a practical time-frame.

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- Order Preserving: Use order-information as well to predict.
 - ⇒ Deep Recurrent Neural Networks (Deep RNNs)
- Trainable: Estimate accurate functions in a practical time-frame.
 Use gradient based approaches.

 Function Approximator: A model that can approximate such distributions.

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⇒ Increase **depth** of Neural Networks.

- Order Preserving: Use order-information as well to predict.
 - ⇒ Deep Recurrent Neural Networks (Deep RNNs)
- **Trainable:** Estimate *accurate* functions in a **practical** time-frame.

Use **gradient** based approaches.

Are they **easy to train**?

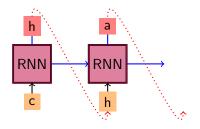
$$x_t = \mathsf{RNN}(x_{t-1}, c_{t-1})$$

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= RNN $(x_{t-1}, x_{t-2}, \dots, x_1)$
= RNN $(x_{1:t-1})$

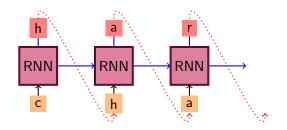
$$\begin{array}{rcl} x_t &=& \mathsf{RNN}\,(x_{t-1},c_{t-1}) \\ &=& \mathsf{RNN}\,(x_{t-1},x_{t-2}\dots,x_1) \\ &=& \mathsf{RNN}\,(x_{1:t-1}) \\ \Rightarrow \mathsf{RNN} &\sim& \mathsf{P}\left(\left\| x_t \right\| x_{1:t-1} \right) \end{array}$$

Language Modeling



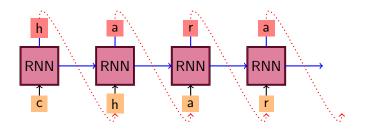
• Note: Blue Arrows correspond to **hidden states** (c_{t-1}) .

Language Modeling



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• Trainability: Vanilla RNNs suffer from the Vanishing Gradient problem,

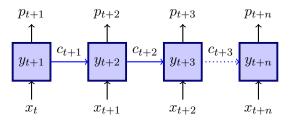


Figure 1: Forward Pass

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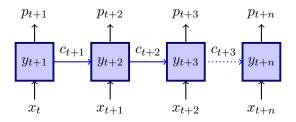


Figure 1: Forward Pass

$$y_{t+1} = \mathbf{X}x_t + \mathbf{C}c_t$$

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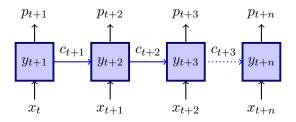


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$$y_{t+1} = \mathbf{X}x_t + \mathbf{C}c_t$$
$$c_{t+1} = \sigma(y_{t+1})$$

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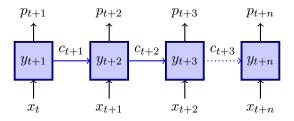


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$$y_{t+1} = \mathbf{X}x_t + \mathbf{C}c_t$$

$$c_{t+1} = \sigma(y_{t+1})$$

$$p_{t+1} = \operatorname{softmax}(\mathbf{W}c_{t+1})$$



Figure 2: Gradients in Vanilla RNN

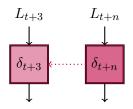


Figure 2: Gradients in Vanilla RNN

 Why?
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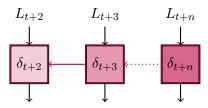


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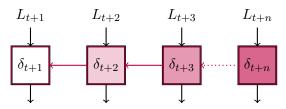


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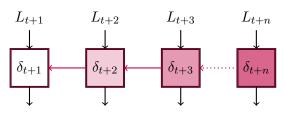


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$$L_j = (p_j^{gt} - p_j)^2$$

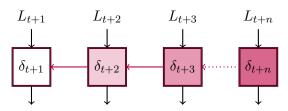


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$$L_{j} = (p_{j}^{gt} - p_{j})^{2}$$

$$\frac{\partial L_{t+n}}{\partial y_{t+1}} = \frac{\partial L_{t+n}}{\partial y_{t+n}} \cdot \frac{\partial y_{t+n}}{\partial y_{t+n-1}} \cdot \dots \frac{\partial y_{t+2}}{\partial y_{t+1}}$$

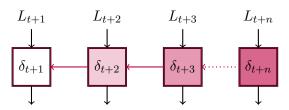


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$$\begin{array}{rcl} L_{j} & = & (p_{j}^{gt} - p_{j})^{2} \\ \frac{\partial L_{t+n}}{\partial y_{t+1}} & = & \frac{\partial L_{t+n}}{\partial y_{t+n}} \cdot \frac{\partial y_{t+n}}{\partial y_{t+n-1}} \cdot \dots \frac{\partial y_{t+2}}{\partial y_{t+1}} \\ & = & \frac{\partial L_{t+n}}{\partial y_{t+n}} \cdot \prod_{\tau=t+2}^{t+n} \frac{\partial y_{\tau}}{\partial y_{\tau-1}} \end{array}$$

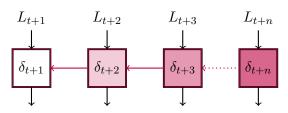


Figure 2: Gradients in Vanilla RNN

$$\prod_{\tau=t+2}^{t+n} \frac{\partial y_{\tau}}{\partial y_{\tau-1}}$$

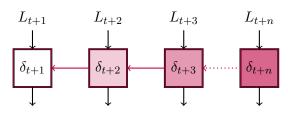


Figure 2: Gradients in Vanilla RNN

$$\prod_{\tau=t+2}^{t+n} \frac{\partial y_{\tau}}{\partial y_{\tau-1}}$$

$$\frac{\partial y_{\tau}}{\partial y_{\tau-1}} = \mathbf{C}^{\mathbf{T}} \sigma' (y_{\tau-1})$$

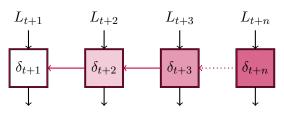


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$$\frac{\partial y_{\tau}}{\partial y_{\tau-1}} = \mathbf{C}^{\mathbf{T}} \sigma' (y_{\tau-1})$$
$$\left\| \frac{\partial y_{\tau}}{\partial y_{\tau-1}} \right\| \leq \|\mathbf{C}\| \frac{1}{4}$$

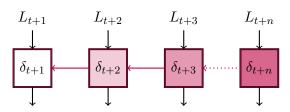


Figure 2: Gradients in Vanilla RNN

$$\frac{\partial y_{\tau}}{\partial y_{\tau-1}} = \mathbf{C}^{\mathbf{T}} \sigma'(y_{\tau-1})$$

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$$\prod_{\tau=t+2}^{t+n} \left\| \frac{\partial y_{\tau}}{\partial y_{\tau-1}} \right\| \leq \left(\|\mathbf{C}\| \frac{1}{4} \right)^{n-1}$$

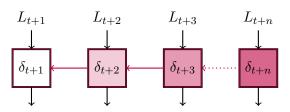


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$$\prod_{\tau=t+2}^{t+n} \frac{\partial y_{\tau}}{\partial y_{\tau-1}}$$

Exponentially Decaying Gradients

$$\frac{\partial y_{\tau}}{\partial y_{\tau-1}} = \mathbf{C}^{\mathbf{T}} \sigma' (y_{\tau-1})$$

$$\left\| \frac{\partial y_{\tau}}{\partial y_{\tau-1}} \right\| \leq \|\mathbf{C}\| \frac{1}{4}$$

$$\prod_{t=0}^{t+n} \left\| \frac{\partial y_{\tau}}{\partial y_{\tau-1}} \right\| \leq (\|\mathbf{C}\| \frac{1}{4})^{n-1}$$

• GRUs/LSTMs alleviate this problem by using gates on inputs, outputs and hidden states [Hochreiter and Schmidhuber, 1997].

$$y_{\tau} = \mathbf{X}x_{\tau} + \mathbf{C}\sigma(y_{\tau-1})$$
 (1)
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$$\approx \mathbf{I}$$

To retain modeling power, introduce a non-linear term

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$$y_{\tau} = \mathbf{X}x_{\tau} + y_{\tau-1} + \mathbf{z} \cdot \phi (y_{\tau-1})$$

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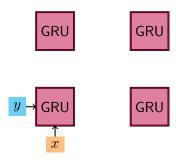
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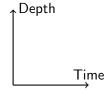
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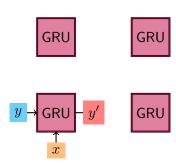
$$y_{\tau} = \mathbf{X}x_{\tau} + y_{\tau-1} + \mathbf{z} \cdot \phi (y_{\tau-1})$$
$$\frac{\partial y_{\tau}}{\partial y_{\tau-1}} \approx \mathbf{I} + \mathbf{z} \cdot \phi' (y_{\tau-1})$$

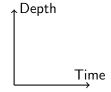
GRU Equations



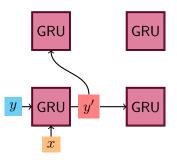


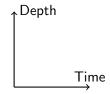
GRU Equations





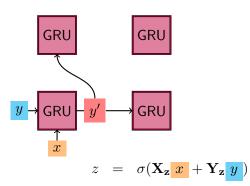
GRU Equations

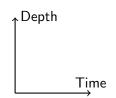




Why?

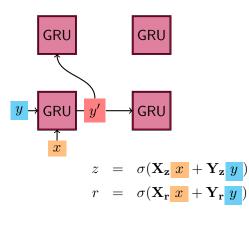
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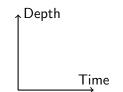




Why?

GRU Equations

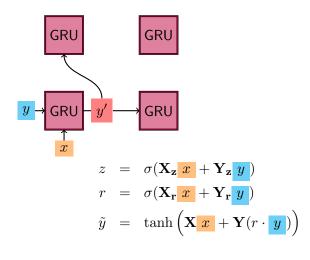


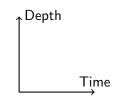


Why?

Motivation

GRU Equations



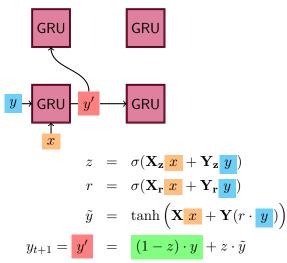


Why?

Motivation

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GRU Equations



Depth

Why?

• Even though the gating mechanisms (i.e. CEC) resolve vanishing gradient issues along time,

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- Gradients have been shown to vanish along depth.

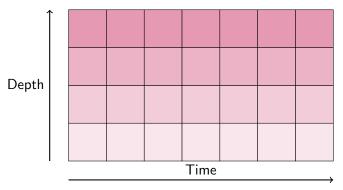


Figure 3: Gradients along Depth in a GRU

 We observe the gradients while training a Deep GRU network on Character-Level Language Model.

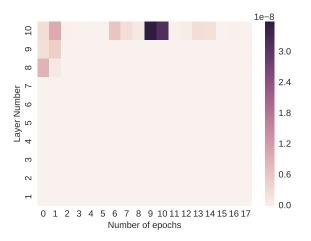
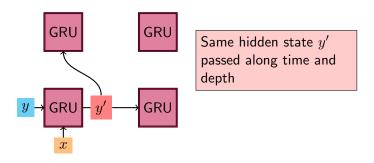
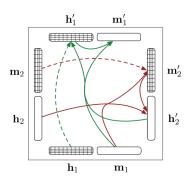


Figure 4: Gradient-Norms across depth in a 10-layered GRU



• Grid-LSTMs [Kalchbrenner et al., 2015] is to have **different hidden** states along time and depth.



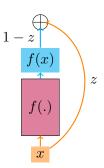
• Recurrent Highway Networks [Zilly et al., 2016] use gating in the depth to enforce **Constant Error Carrousel**.



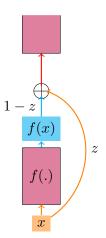
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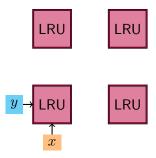
while enforcing Constant Error Carrousel ?

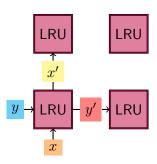
Is it possible to design a Recurrent Unit

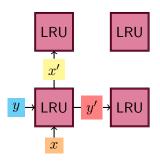
that passes different hidden states along depth and time

while enforcing Constant Error Carrousel ?

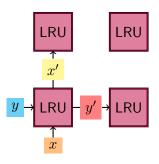
YES!!!





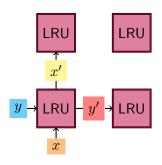


$$z = \sigma(\mathbf{X_z} \ x + \mathbf{Y_z} \ y)$$

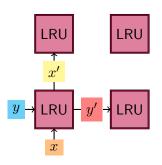


$$z = \sigma(\mathbf{X_z} \ x + \mathbf{Y_z} \ y)$$
$$r = \sigma(\mathbf{X_r} \ x + \mathbf{Y_r} \ y)$$

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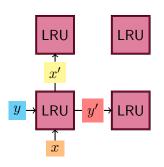


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$$r = \sigma(\mathbf{X_r} \ \boldsymbol{x} + \mathbf{Y_r} \ \boldsymbol{y})$$
$$q = \sigma(\mathbf{X_q} \ \boldsymbol{x} + \mathbf{Y_q} \ \boldsymbol{y})$$



$$\tilde{x} = \tanh\left(\mathbf{X}_{\mathbf{x}} \mathbf{x} + \mathbf{Y}_{\mathbf{x}} \left(r \cdot \mathbf{y}\right)\right)$$

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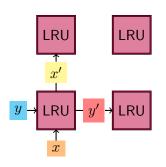


$$z = \sigma(\mathbf{X}_{\mathbf{z}} \mathbf{x} + \mathbf{Y}_{\mathbf{z}} \mathbf{y})$$
$$r = \sigma(\mathbf{X}_{\mathbf{r}} \mathbf{x} + \mathbf{Y}_{\mathbf{r}} \mathbf{y})$$
$$q = \sigma(\mathbf{X}_{\mathbf{q}} \mathbf{x} + \mathbf{Y}_{\mathbf{q}} \mathbf{y})$$

$$\tilde{x} = \tanh \left(\mathbf{X_x} \cdot \mathbf{x} + \mathbf{Y_x} \left(r \cdot \mathbf{y} \right) \right)$$

 $\tilde{y} = \tanh \left(\mathbf{Y_y} \cdot \mathbf{y} + \mathbf{X_y} \left(q \cdot \mathbf{x} \right) \right)$

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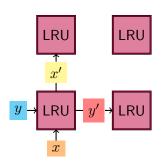
$$z = \sigma(\mathbf{X_z} \ x + \mathbf{Y_z} \ y)$$
$$r = \sigma(\mathbf{X_r} \ x + \mathbf{Y_r} \ y)$$
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$$x_{t+1} = \boldsymbol{x'} = z \cdot \tilde{y} + (1-z) \cdot \boldsymbol{x}$$

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$$z = \sigma(\mathbf{X_z} x + \mathbf{Y_z} y)$$

$$r = \sigma(\mathbf{X_r} x + \mathbf{Y_r} y)$$

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$$y_{t+1} = \mathbf{y}' = z \cdot \tilde{x} + (1-z) \cdot \mathbf{y}$$

Formulation

Task: Character Level Language Modeling

• Out of Vocabulary Words can potentially be modeled.

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- Character Aware Neural Language Models [Kim et al., 2016]

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- Out of Vocabulary Words can potentially be modeled.
- Character Aware Neural Language Models [Kim et al., 2016]
- Speech Synthesis [Wang et al., 2017]

Datasets

• We take 2 datasets **Penn Tree Bank** and **War and Peace**.

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Datasets

- We take 2 datasets Penn Tree Bank and War and Peace.
- Each of them has around 5 million characters.

War and Peace (WP)

Well, Prince, so Genoa and Lucca are now just family estates of the Bonapartes. But I warn you, if you don't tell me that this means war, if you still try to defend the infamies and horrors perpetrated by that Antichrist–I really believe he is Antichrist–I will have nothing more to do with you and you are no longer my friend, no longer my 'faithful slave,' as you call yourself!

Penn Tree Bank (PTB)

the asbestos fiber <unk> is unusually <unk> once it enters the <unk> with even brief exposures to it causing symptoms that show up decades later researchers said, <unk> inc. the unit of new york-based <unk> corp. that makes kent cigarettes stopped using <unk> in its <unk> cigarette filters in N.

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Experimental Setup

Multi-Class Classification Problem

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Experimental Setup

- Multi-Class Classification Problem
- Categorical Cross-Entropy Loss
 - loss = $\sum_{\forall i \in \mathcal{C}} p_i \log(\hat{p}_i)$ where \mathcal{C} is the set of all classes.

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• RNN unrolled 50 time-steps in time.

Experimental Questions

• Accuracy: For equal number of parameters does the loss improve?

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- Accuracy: For equal number of parameters does the loss improve?
- **Convergence Rate:** How many epochs does it take for the model to converge?
- Trainability: How are the gradient norms distributed across layers?

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Table 1: Penn Treebank Dataset and losses are in bits per character (BPC). Lower is better. l is the number of layers.

| | Hidden | | | | |
|-------|--------|-------|-------|-------|-------|
| Model | l=2 | l=4 | l=6 | l = 8 | Units |
| GRU | 1.107 | 1.092 | 1.125 | 2.99 | 387 |

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| Highway | 1.110 | 1.102 | 1.107 | - | - |
| LRU | 1.097 | 1.102 | 1.101 | 1.103 | 300 |

Table 2: War and Peace Dataset and losses are in bits per character (BPC). Lower is better. l is the number of layers.

| | Hidden | | | | |
|-------|--------|-------|-------|-------|-------|
| Model | l=2 | l=4 | l=6 | l = 8 | Units |
| GRU | 1.285 | 1.293 | 1.344 | 3.104 | 387 |

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| Model | l=2 | l=4 | l=6 | l = 8 | Units |
| GRU | 1.285 | 1.293 | 1.344 | 3.104 | 387 |
| LSTM | 1.297 | 1.353 | 1.530 | 3.100 | 335 |

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| LSTM | 1.297 | 1.353 | 1.530 | 3.100 | 335 |
| GLSTM | 1.319 | 1.317 | 1.312 | 1.31 | 237 |
| Highway | 1.294 | 1.298 | 1.306 | 1.305 | - |

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| GLSTM | 1.319 | 1.317 | 1.312 | 1.31 | 237 |
| Highway | 1.294 | 1.298 | 1.306 | 1.305 | - |
| LRU | 1.279 | 1.280 | 1.281 | 1.287 | 300 |

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Results - Convergence Rates

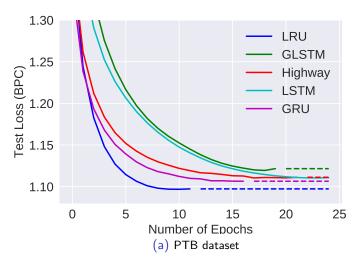


Figure 5: Convergence rates of various models on PTB and WP datasets.

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Results - Convergence Rates

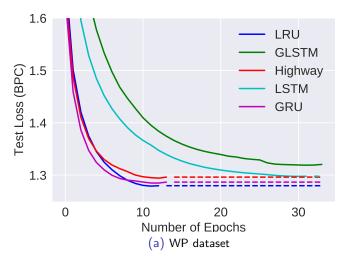


Figure 5: Convergence rates of various models on PTB and WP datasets.

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Results - Trainability

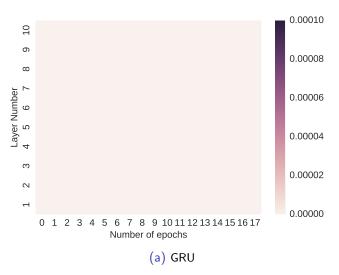


Figure 6: Gradient Norms across layers and number of epochs as a heatmap. Darker values are bigger.

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Results - Trainability

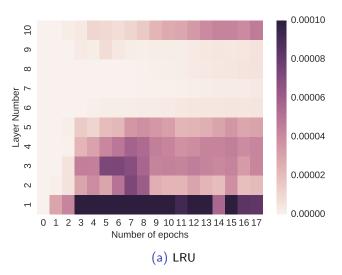


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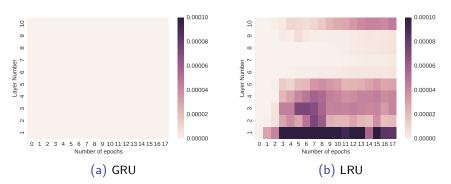


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Conclusions

• Faster convergence rates for LRU

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- Gradients are spread out across the layers. Hence **alleviation** of vanishing gradients.

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- Faster convergence rates for LRU
- Gradients are spread out across the layers. Hence alleviation of vanishing gradients.
- While **not aggravating** the performance.

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References I



Hochreiter, S. and Schmidhuber, J. (1997).

Long short-term memory.

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Thank You

